

MXYx 2 axes

● Moving arm type ● Cable carrier

Ordering method

MXYx-C	[]	[]	[]	[]	RCX222	[]	R	[]	[]
Model	Cable	Combination	X-axis stroke	Y-axis stroke	Cable length	Controller	Usable for CE	Regenerative unit	Input/Output selection 1

M1	25 to 125cm	15 to 55cm	3L: 3.5m (Standard)
M3	5L: 5m		
	10L: 10m		

RCX222

R

[]

No entry: Standard	E: CE marking
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Regenerative unit

[]

Input/Output selection 1

[]

Input/Output selection 2

[]

No entry: None

N1: OP.DIO24/16
N2: RG2 (RCX222)
R: RGU-2 (DRCX)

P: PNP

CC: CC-Link

DN: DeviceNet

PB: Profibus

EN: Ethernet

Y: YC-Link

EN: Ethernet

Y: YC-Link

Note 1: NPN and Ethernet cannot be selected if using CE marking.

Note 2: Available only for the master.

Note 3: Only when CC or DN or PB was selected for I/O select 1 above. EN can be selected in I/O select 2.

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

	X-axis	Y-axis
Axis construction Note 1	F17	F14H
AC servo motor output (W)	400	200
Repeatability Note 2 (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20
Maximum speed Note 3 (mm/sec)	1200	1200
Moving range (mm)	250 to 1250	150 to 550
Robot cable length (m)	Standard: 3.5 Option: 5,10	

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3: When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

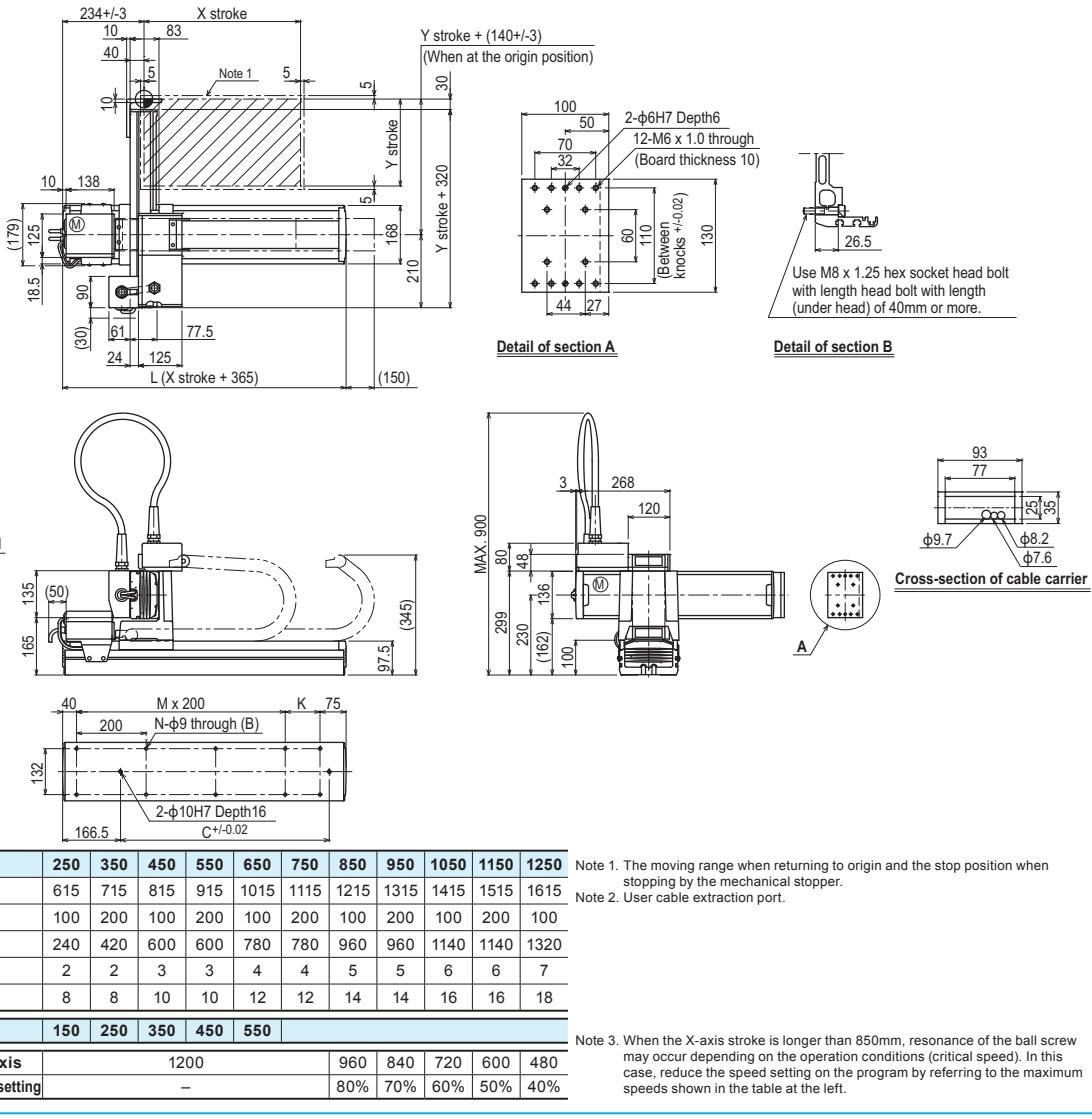
Specification

Y stroke (mm)	XY 2 axes
150 to 550	20

Controller

Controller	Operation method
RCX222-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication
DRCX2010-R	

MXYx 2 axes M1



APPLICATION	Compact TRANSERO
FLIP-X	Single-axis robots
PHASER	Linear motor single-axis robots
XY-X	Cartesian robots
YK-XG	SCARA robots
YP-X	Pick & place robots
CLEAN	
CONTROLLER	
INFORMATION	
Arm type	
Gantry type	
Moving arm type	
Pole type	
XZ type	

MXYx 2 axes M3

